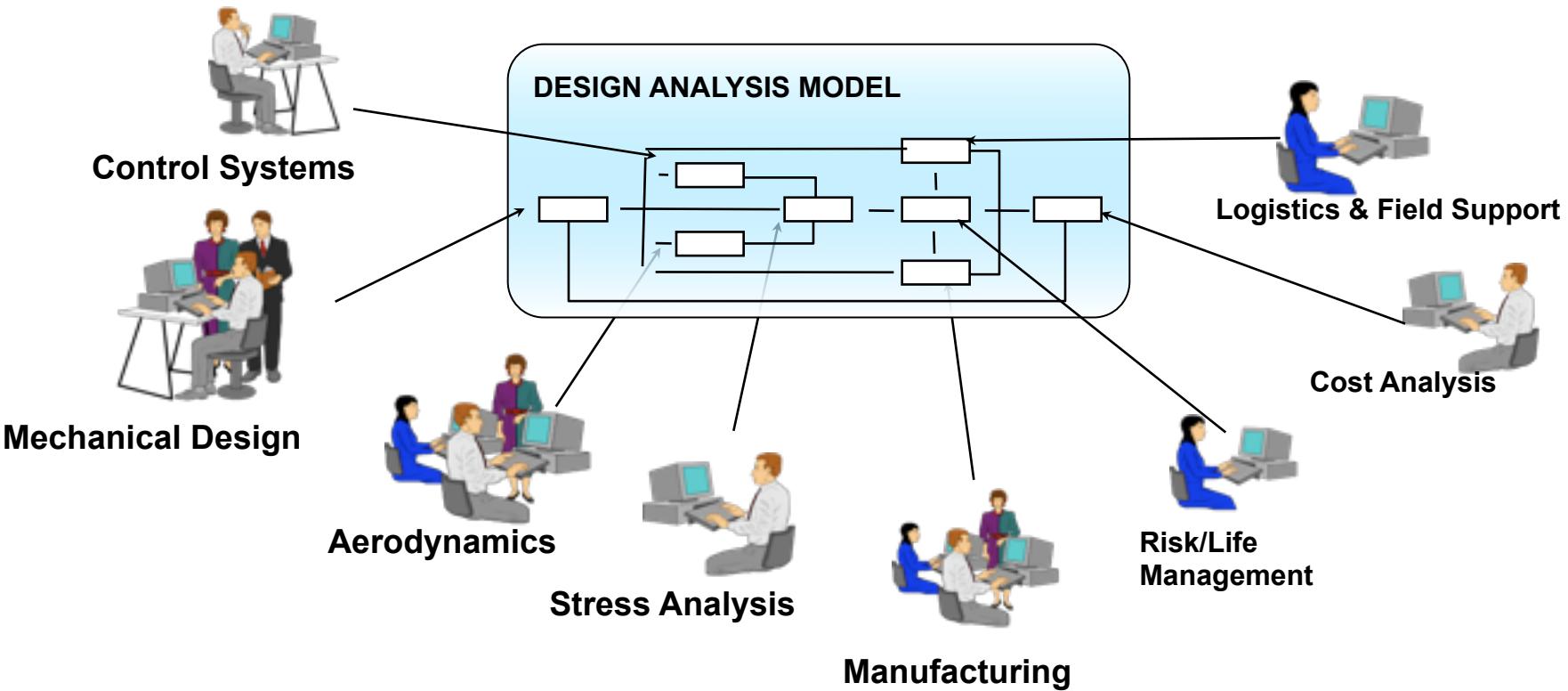


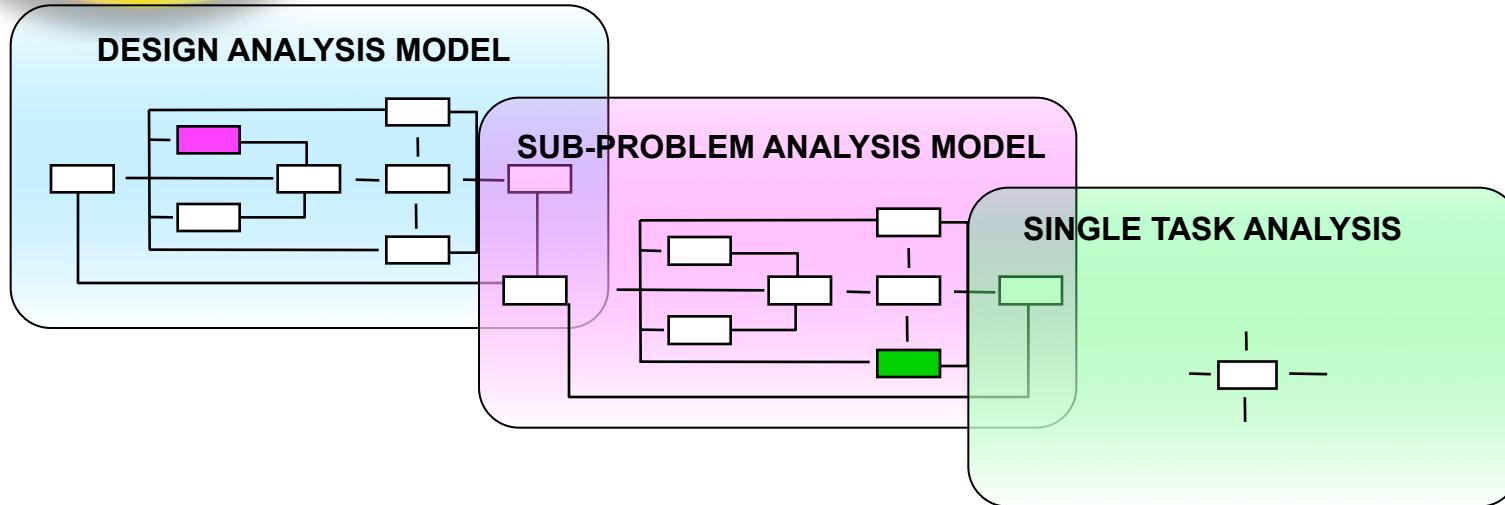
Complex system optimisation with modeFRONTIER

Carlo Poloni
University of Trieste
&
President - ESTECO srl

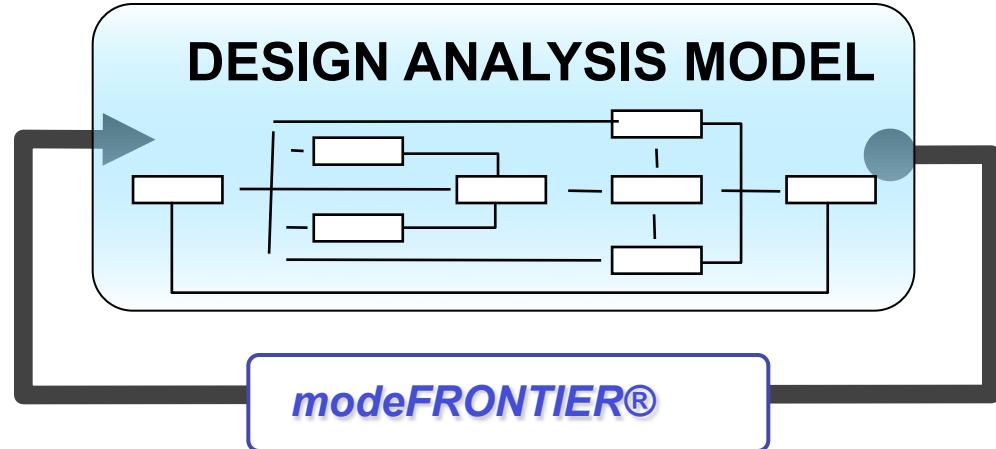
Design Process



Decomposed design process



- Design Of Experiment
- Optimisation algorithms
- Decision Making Procedures



Integrating Multibody Simulation and CFD: toward Complex Multidisciplinary Design Optimization

[Stefano PIERI^{1\)}](#), [Carlo POLONI^{2\)}](#) and [Martin MÜHLMEIER^{3\)}](#)

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This paper describes the use of integrated multidisciplinary analysis and optimization of a race car model on a predefined circuit. The objective is the definition of the most efficient geometric configuration that can guarantee the lowest lap time. In order to carry out this study it has been necessary to interface the design optimization software *modeFRONTIER* with the following softwares: *CATIA v5*, a three dimensional CAD software, used for the definition of the parametric geometry; *A.D.A.M.S./Motorsport*, a multi-body dynamic simulation software; *IcemCFD*, a mesh generator, for the automatic generation of the CFD grid; *CFX*, a Navier-Stokes code, for the fluid-dynamic forces prediction. The process integration gives the possibility to compute, for each geometrical configuration, a set of aerodynamic coefficients that are then used in the multibody simulation for the computation of the lap time. Finally an automatic optimization procedure is started and the lap-time minimized. The whole process is executed on a Linux cluster running CFD simulations in parallel.

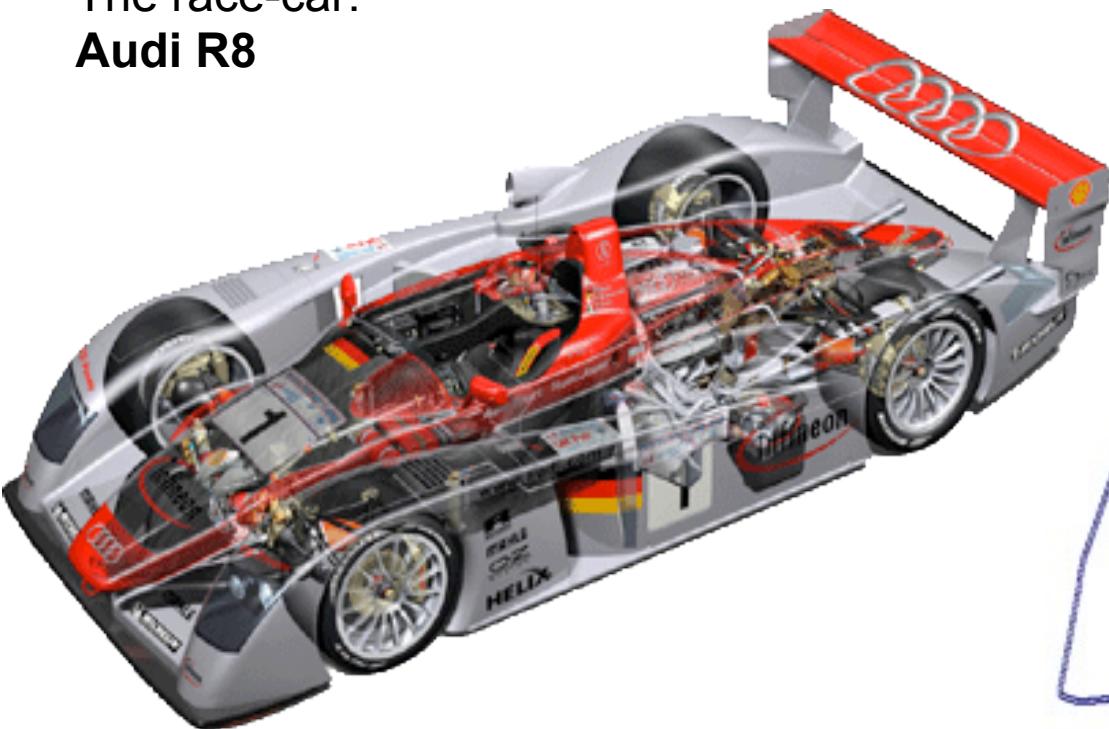
Key Words:

[Automobile](#), [Computer Aided Design \(CAD\)](#), [Optimum Design](#), [Computational Fluid Dynamics](#), [Dynamic Programming](#)

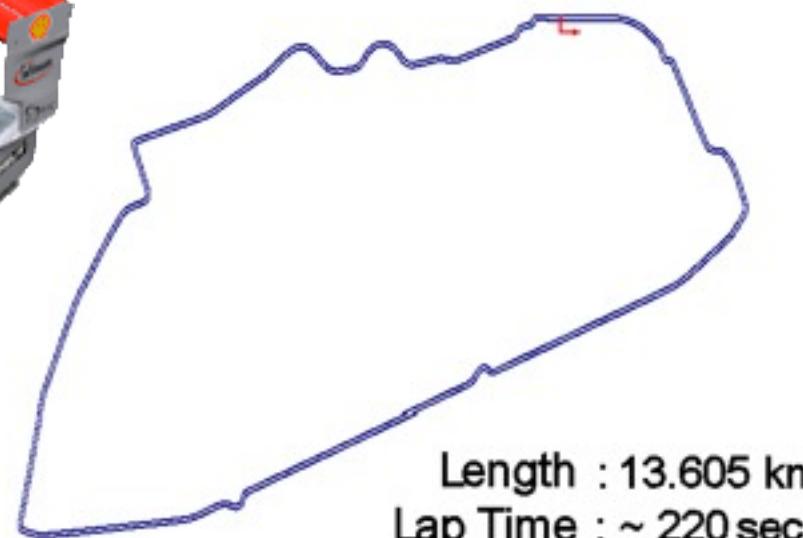


The problem

The race-car:
Audi R8



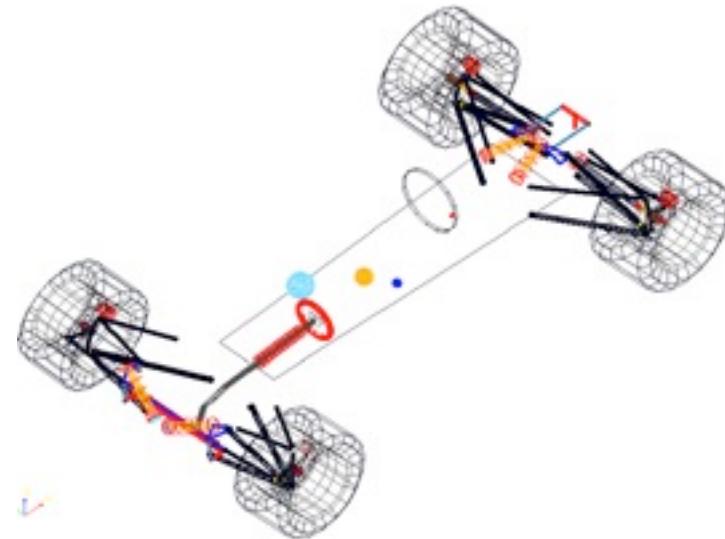
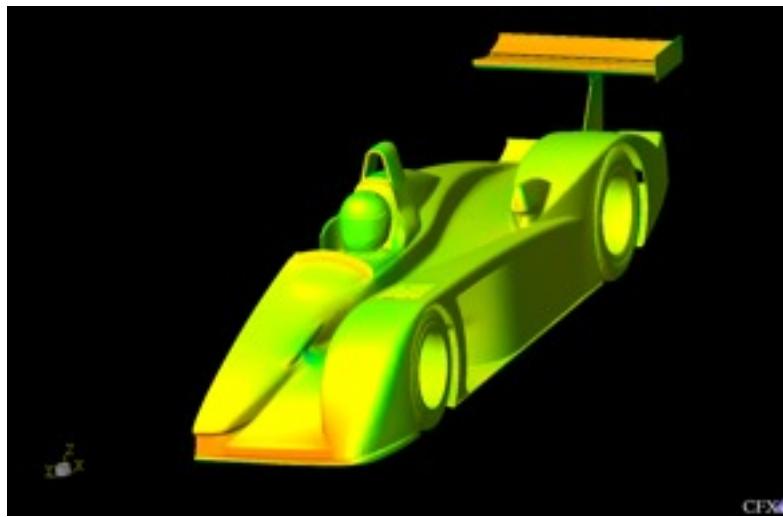
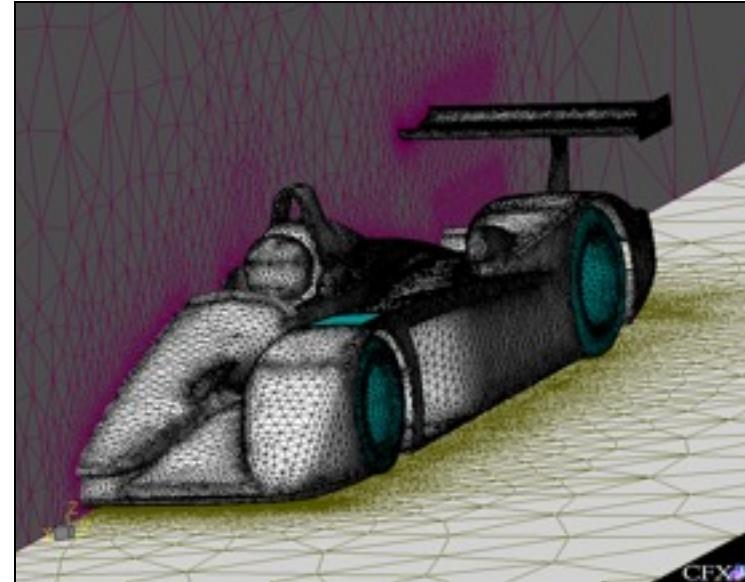
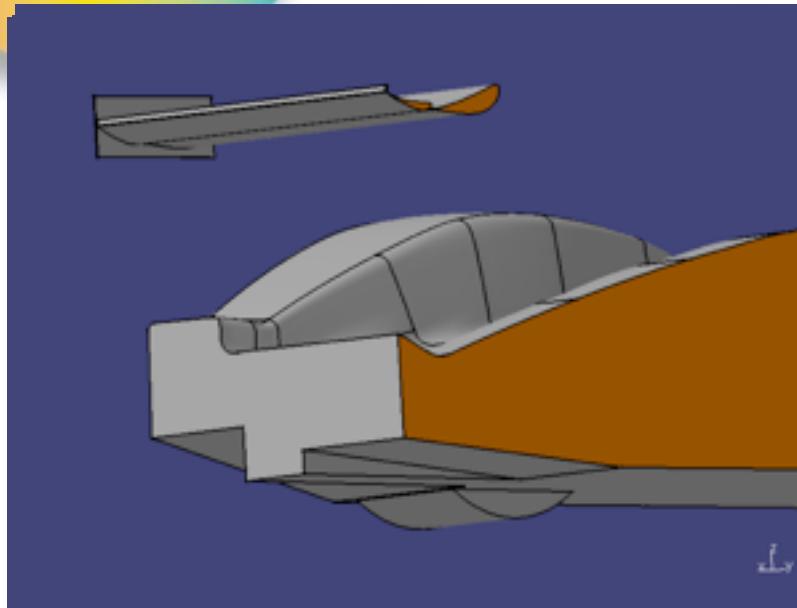
The track:
Le Mans



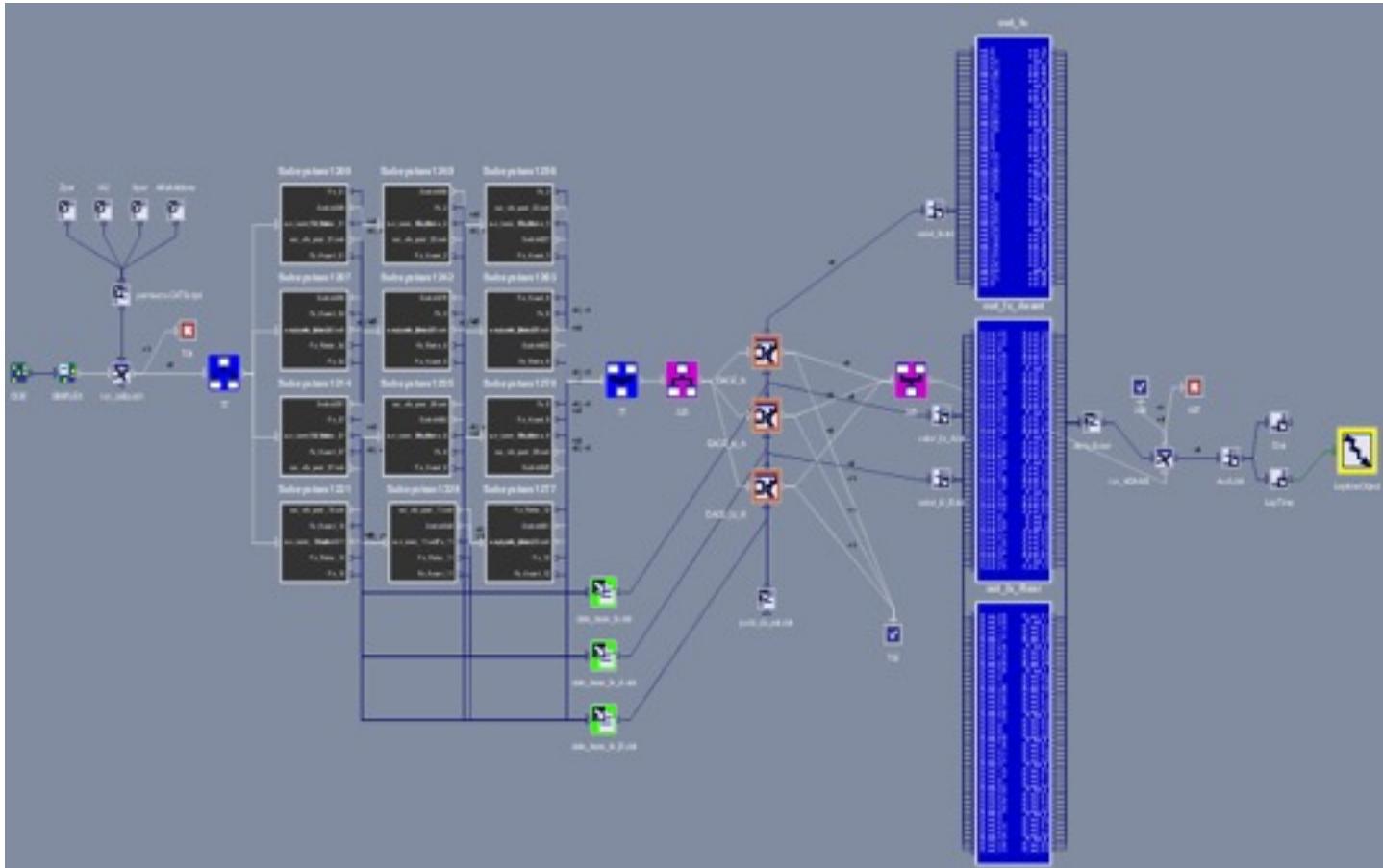
Racing from 2000 to 2006 - 1st at 24h Le Mans 5 times



The physics (numerics?!?)



400+ “software activations” are needed



Handling of uncertainties...

When facing “creative design” uncertainties in the performance prediction must be taken into account:

- Noise due to unpredictable environment
- Noise due to geometrical tolerances
- Numerical inaccuracies

Different tools are available in modeFRONTIER to face these issues:

- statistical tools for DFSS
- RSM methodology
- MORDO techniques



Porsche911-GTO (McNish) **Le Mans '98**

<http://www.dailymail.co.uk/news/article-2002561/Pictures-Allan-McNish-crash-Le-Mans-24-hour-race.html>

Explore new Frontiers of Innovation

Model: open wheel car

Software: VI-Car_Real_Time

Targets:

Increase AVG speed

Minimize the Steer Oscillations

Standard Parameters (10):

Setup of the car:

front/rear ride_heights (2)

front/rear springs_stiffesses (2)

front/rear antirollbar_stiffnesses (2)

front/rear dampers scaling factors (2)

Limited Slip Differential setting:

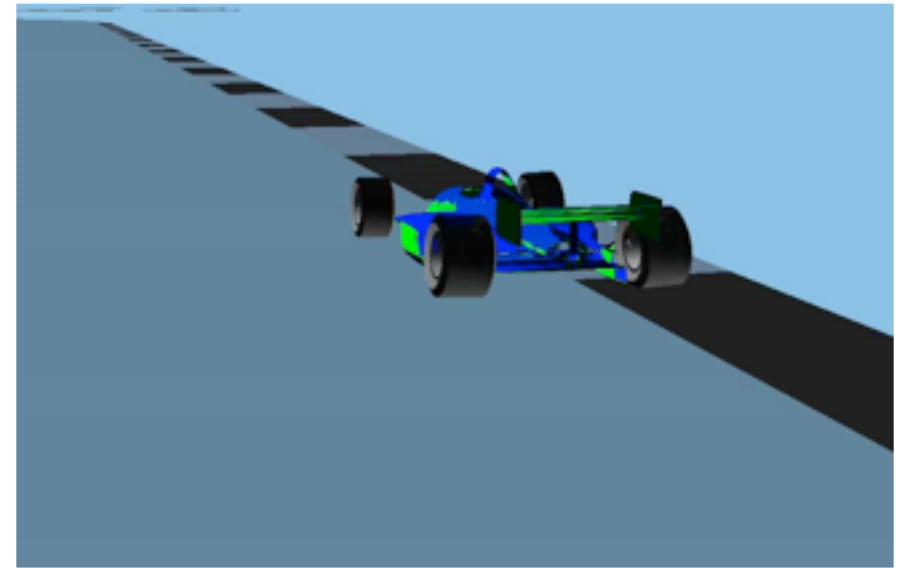
C0 coefficient  Preload (1)

C1 coefficient (1)

Stochastic Parameters (3):

Driver behaviour: preview_time (1)

Tires: front/rear lateral grip factor (2)

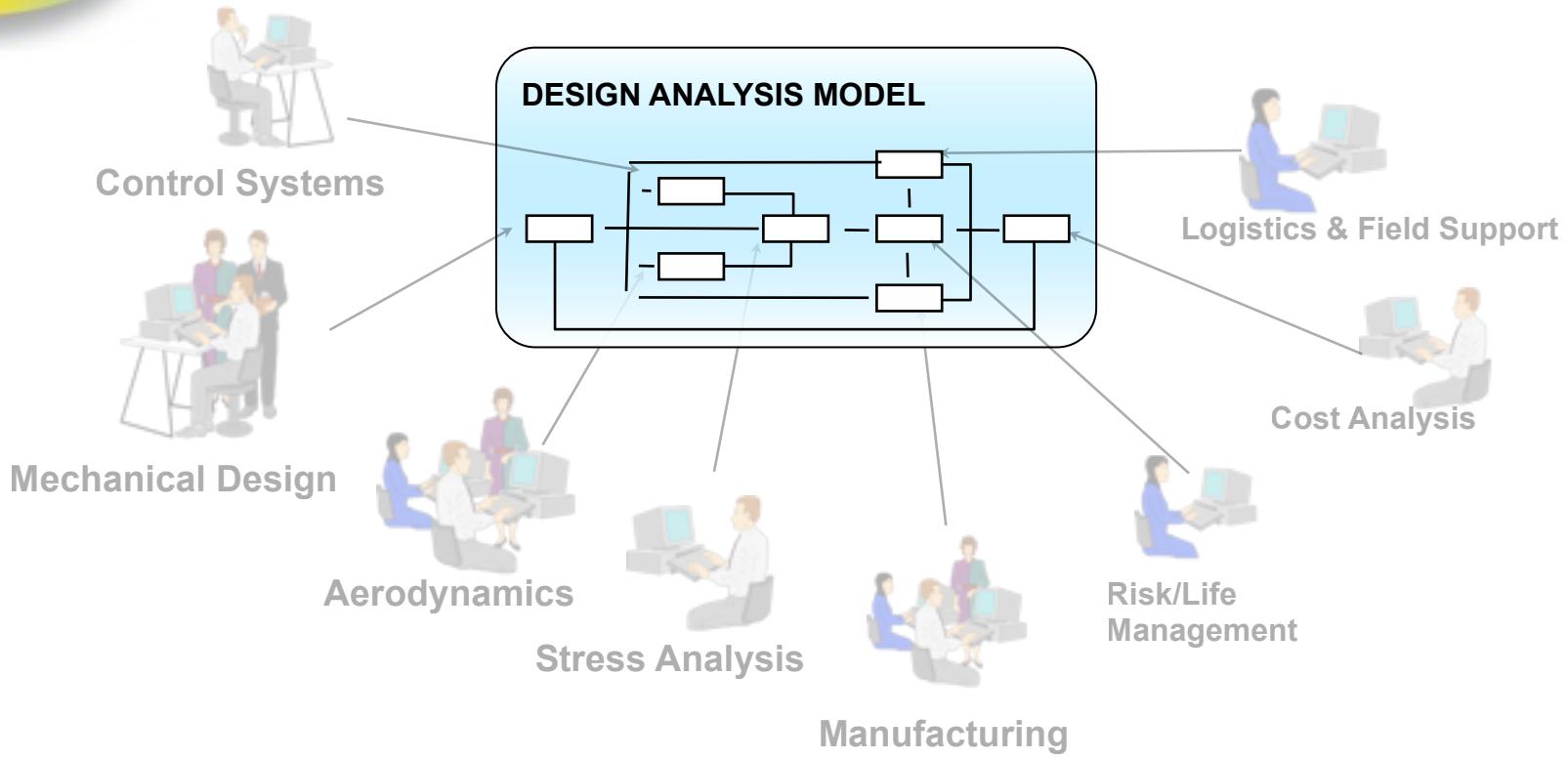


Intensive computation for:

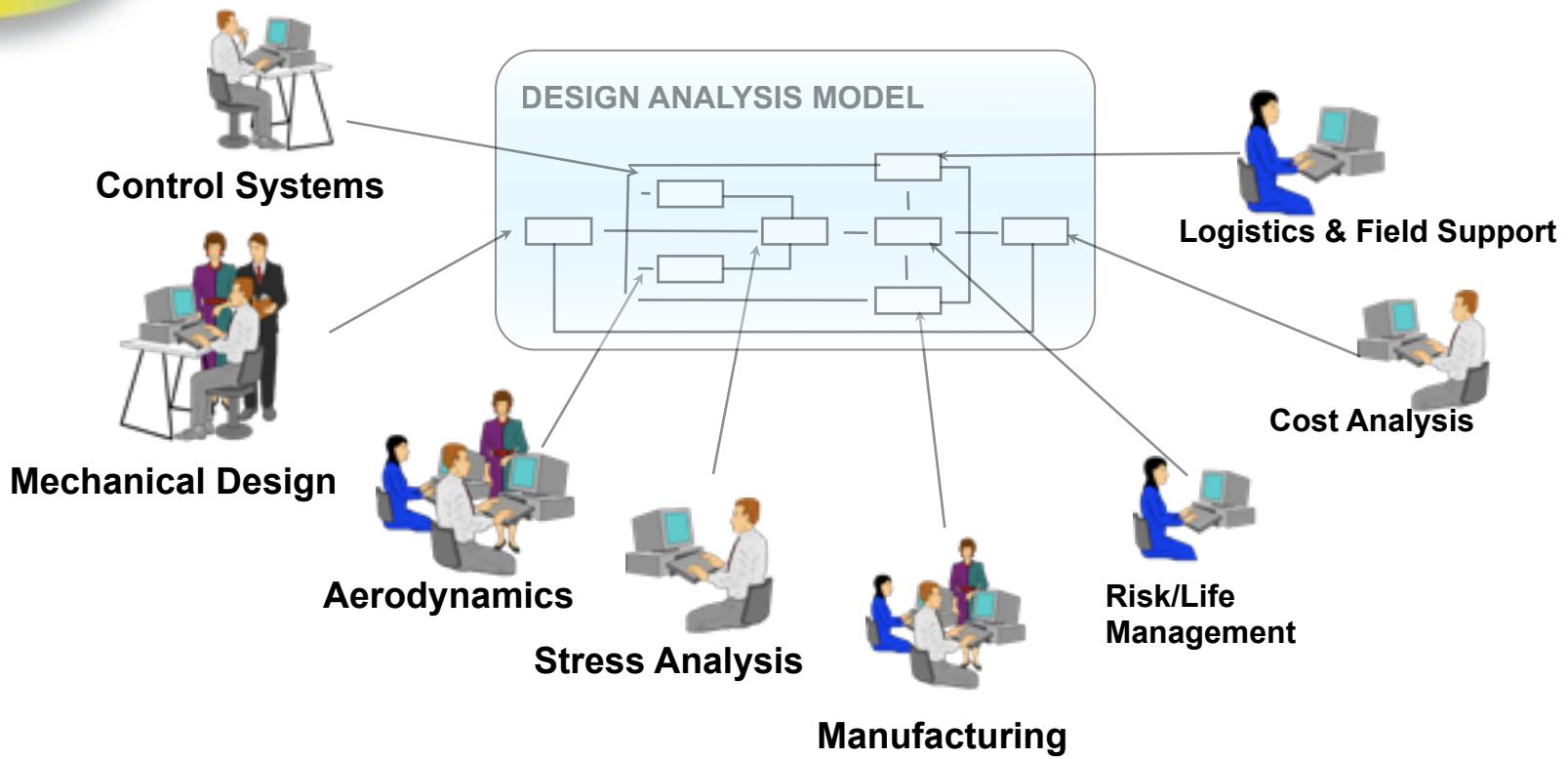
- For more accurate prediction
- For multiple simulation



Design Process



Design Process



Cooperation through IT communication standards



Our Strengths

modeFRONTIER® 5
Service Oriented
Architecture

modeFRONTIER®
multi objective design
environment

Enterprise
Solutions, "Let
everybody use the
technology"

Numerics, "Where
is the Optimum"

modeFRONTIER® 3.x

Present

**modeFRONTIER®
4.x**

Future

Data Mining, "Why it
is Optimum"



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